

/\* iLoopino 1.00 - May 2016

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\* Permission is DENIED for commercial use and / or profit.

\* Most of this code is based on codes found on the Net and libraries, though the assembling

\* of codes in a "structured programm" as well most of core part, has been done by me, with a lot of time effort, and lots of help

\* from many good guys all over the World, specially the one at arduino.cc.

\* So, if you're going to use/modify this code would you please visit my guitar effects page and "like" it :) ;) ;)

\* here's the link to my page <https://www.facebook.com/4kfx2/?ref=bookmarks>

\* and, may be, leave a message if you pass by.

\* For any question you can contact me on FB  
<https://www.facebook.com/armando.colangelo.5> \*/

```
#include "OneButton.h"
```

```
#include "Bounce2.h"
```

```
#include <EEPROM.h>
```

```
#define DEBOUNCE 5 // how many ms to debounce, 5+ ms is usually plenty
```

```
#define Trigger_Button 7 // TRIGGER BUTTON
```

```
#define Trigger_LED 6 //TRIGGER LED
```

```
#define mutePin 14
```

```
///

```
#define NUMBUTTONS sizeof(buttons)
```


```

```
byte h = 0, v = 0; //variables used in for loops
```

```
const unsigned long period = 50; //little period used to prevent error
```

```
unsigned long kdelay = 0; // variable used in non-blocking delay
```

```
const byte rows = 2; //number of rows of keypad
```

```
const byte columns = 3; //number of columnss of keypad
```

```
const byte Output[rows] = {16, 15}; //array of pins used as output for rows of keypad

const byte Input[columns] = {19, 18, 17}; //array of pins used as input for columnss of keypad

byte buttons[] = {19, 18, 17, 16, 15};

int whichPreset;

int beatdelay = 1200;

int savedPreset = 0;

int event = 0;

int Dmute = 50;

int Preseton;

int WPreseton;

//int changeLoop = 0;

int sumofButtonspressed;

int oldSwitchSumButton = 0;

int relayPin[] = {5, 4, 3, 2, 1, 0};

int ledPin[] = {8, 9, 10, 11, 12, 13};

int triggerDelay = 0;

int SwitchSumButton = 0;

int sumSingle = 0;

int StateofbuttonSingle = 0;

int i = 0;

//int oldquale = 0;

int oldsingleButtonStatus = 0;

int veryBeginning = 1;

int singleButtonStatus = 0;

int debounce = 20; // ms debounce period to prevent flickering when pressing or releasing the button

int DCgap = 250; // max ms between clicks for a double click event
```

```

int holdTime = 2000; // ms hold period: how long to wait for press+hold event

int longHoldTime = 3000; // ms long hold period: how long to wait for press+hold event

int ExtralongHoldTime = 4000; // ms long hold period: how long to wait for press+hold
event

const int releDelay = 470; //delay before and after mute-unmute

boolean state; /*initial state of each key = false*/

//determine how big the array up above is, by checking the size

//track if a button is just pressed, just released, or 'currently pressed'

//byte pressed[NUMBUTTONS], justpressed[NUMBUTTONS], justreleased[NUMBUTTONS];

//byte previous_keystate[NUMBUTTONS], current_keystate[NUMBUTTONS];

boolean buttonVal = HIGH; // value read from button

boolean buttonLast = HIGH; // buffered value of the button's previous state

boolean DCwaiting = false; // whether we're waiting for a double click (down)

boolean DConUp = false; // whether to register a double click on next release, or whether to
wait and click

boolean singleOK = true; // whether it's OK to do a single click

long downTime = -1; // time the button was pressed down

long upTime = -1; // time the button was released

boolean ignoreUp = false; // whether to ignore the button release because the click+hold
was triggered

boolean waitForUp = false; // when held, whether to wait for the up event

boolean holdEventPast = false; // whether or not the hold event happened already

boolean longHoldEventPast = false; // whether or not the long hold event happened already

boolean ExtralongHoldEventPast = false;

void setup() {

// writetempEprom();// REMOVE BEFORE FINAL PROJECT

pinMode(Trigger_Button, INPUT_PULLUP);

pinMode(Trigger_LED, OUTPUT);

```

```

for (i = 0; i < 6; i++) {
    pinMode(relayPin[i], OUTPUT);
    pinMode(ledPin[i], OUTPUT);
}

for (i = 0; i < 6; i++) {
    pinMode(buttons[i], INPUT_PULLUP);
    digitalWrite(buttons[i], HIGH);
}

pinMode(mutePin, OUTPUT); // MUTE Pin

for (byte i = 0; i < rows; i++) { //for loop used to make pin mode of outputs as output
    pinMode(Output[i], OUTPUT);
}

for (byte s = 0; s < columns; s++) { //for loop used to make pin mode of inputs as
inputpullup
    pinMode(Input[s], INPUT_PULLUP);
}

startupBlinking();
}

void loop() {
    //delay(300);

    int singleButtonStatus = checkButton();

    if (oldsingleButtonStatus == 4 && singleButtonStatus == 1) { // upon exit 3-save turns off all
LEDs/relays then recall saved preset

        delay(Dmute);

        mute();

        AllPresetLedsOff();

        AllPresetRelaysOff();

        delay(600);
    }
}

```

```

SwitchSumButton = 10 + savedPreset;

SwitchCore();

delay(Dmute);

unmute();

}

if (oldsingleButtonStatus == 5 && singleButtonStatus == 1) { // upon exit 4-bypass turns off
all LEDs/relays then recall last active loop

    delay(Dmute);

    mute();

    AllPresetLedsOff();

    AllPresetRelaysOff();

    delay(600);

    SwitchSumButton = EEPROM.read(150);

    SwitchCore();

    delay(Dmute);

    unmute();

}

if (oldsingleButtonStatus != singleButtonStatus && singleButtonStatus != 0)

{

    oldsingleButtonStatus = singleButtonStatus;

    if (oldsingleButtonStatus == 3) // 3 = build loop -

    {

        //   changeLoop = 1;

        buildtempLoop(); // check rele status of selected preset, if rele is on turn on the
respective LED, otherwise off

    }

    else

    {

```

```

//  changeLoop = 0;
}

StateofbuttonSingle = oldsingleButtonStatus;

triggerDelay = 380 - (oldsingleButtonStatus * 60); // 3 different delay time based on single
button

if (oldsingleButtonStatus == 1) { // return to liveMode, presets can be selected

  if (veryBeginning != 0) {

    blinkLedfortesting();

    greenSingleledoff();

    triggerDelay = 80;

    redSingleledblink();

    redSingleledon();

  }

  redSingleledon();

  if (veryBeginning == 0) {

    SwitchSumButton = EEPROM.read(150); // at startup load last used preset before turn
off

    SwitchCore();

  }

}

if (oldsingleButtonStatus == 3) { //modify preset

  StateofbuttonSingle = 2;

  redSingleledoff();

  greenSingleledblink();

  greenSingleledon();

}

if (oldsingleButtonStatus == 4 ) { //save preset

  StateofbuttonSingle = 3;

```

```

    greenSingleledblink();
    greenSingleledon();
}
if (oldsingleButtonStatus == 5) { //bypass
    beatdelay = 1200;
    StateofbuttonSingle = 4;
    triggerDelay = 80;
    for (int i = 0; i < 12; i++)
    {
        AllPresetLedsOn();
        delay(50);
        AllPresetLedsOff();
        delay(50);
    }
    byPassAll();
}
sumSingle = StateofbuttonSingle * 10; // sumsingle is needed to build a case for switch
// oldquale = 0;
}
/* if (oldsingleButtonStatus == 5) //alternate blinking *** noisy ***
{
    blinkledinByPassMode();
}*/
if (oldsingleButtonStatus == 3 || oldsingleButtonStatus == 4) // rimuovere
oldsingleButtonStatus == 4 se difficoltosa la selezione del preset da salvare
{
    beatdelay = 70;

```

```
whichPreset = EEPROM.read(150) - 11;

blinkledpresetmod(whichPreset);
}

if (millis() - kdelay > period) //used to make non-blocking delay
{
    kdelay = millis(); //capture time from millis function

    switch (keypad()) //switch used to specify which button
    {
        case 0://1

            SwitchSumButton = sumSingle + 1; // sum single+1-6 buttons to build a variable for
case switch

            break;

        case 1://2

            SwitchSumButton = sumSingle + 2;

            break;

        case 2://3

            SwitchSumButton = sumSingle + 3;

            break;

        case 4://4

            SwitchSumButton = sumSingle + 4;

            break;

        case 5://5

            SwitchSumButton = sumSingle + 5;

            break;

        case 6://6

            SwitchSumButton = sumSingle + 6;

            break;
```

```

    default:
        ;
    }
}

if ((oldSwitchSumButton != SwitchSumButton) && (SwitchSumButton < 21 ||
(SwitchSumButton > 26 && SwitchSumButton < 41)))
{
    oldSwitchSumButton = SwitchSumButton;

    SwitchCore();
}

if ((oldSwitchSumButton != SwitchSumButton) && (SwitchSumButton > 20 &&
SwitchSumButton < 27) || (SwitchSumButton > 40 && SwitchSumButton < 47))
{
    if (millis() - kdelay > period) //used to make non-blocking delay
    {
        kdelay = millis(); //capture time from millis function

        switch (keypad()) //switch used to specify which button
        {
            case 0://1

                SwitchSumButton = sumSingle + 1; // sum single+1-6 buttons to build a variable for
case switch

                break;

            case 1://2

                SwitchSumButton = sumSingle + 2;

                break;

            case 2://3

                SwitchSumButton = sumSingle + 3;

                break;

```

```

case 4://4

    SwitchSumButton = sumSingle + 4;

    break;

case 5://5

    SwitchSumButton = sumSingle + 5;

    break;

case 6://6

    SwitchSumButton = sumSingle + 6;

    break;

default:

    ;

}

}

SwitchCore();

if (SwitchSumButton > 20 && SwitchSumButton < 27) {

    SwitchSumButton = 0;

}

if (SwitchSumButton > 40 && SwitchSumButton < 47) {

    SwitchSumButton = 0;

}

}

} //END void loop()

int checkButton() // check single button for single/double/hold

{

    event = 0;

    if (veryBeginning == 0)

    {

```

```

buttonVal = digitalRead(Trigger_Button); // Read the state of the button

if (buttonVal == LOW && buttonLast == HIGH && (millis() - upTime) > debounce) { //
Button pressed down

    downTime = millis();

    ignoreUp = false;

    waitForUp = false;

    singleOK = true;

    holdEventPast = false;

    longHoldEventPast = false;

    ExtralongHoldEventPast = false;

    if ((millis() - upTime) < DCgap && DConUp == false && DCwaiting == true) DConUp =
true;

    else DConUp = false;

    DCwaiting = false;

}

else if (buttonVal == HIGH && buttonLast == LOW && (millis() - downTime) > debounce)
{ // Button released

    if (not ignoreUp) {

        upTime = millis();

        if (DConUp == false) DCwaiting = true;

        else {

            event = 2;

            DConUp = false;

            DCwaiting = false;

            singleOK = false;

        }

    }

}

}

```

```

    if ( buttonVal == HIGH && (millis() - upTime) >= DCgap && DCwaiting == true && DConUp
== false && singleOK == true ) { // Test for normal click event: DCgap expired

    event = 1;

    DCwaiting = false;

}

if (buttonVal == LOW && (millis() - downTime) >= holdTime) { // Test for hold

if (not holdEventPast) { // Trigger "normal" hold

    event = 3;

    waitForUp = true;

    ignoreUp = true;

    DConUp = false;

    DCwaiting = false;

    //downTime = millis();

    holdEventPast = true;

}

if ((millis() - downTime) >= longHoldTime) { // Trigger "long" hold

    if (not longHoldEventPast) {

        event = 4;

        longHoldEventPast = true;

    }

}

if ((millis() - downTime) >= ExtralongHoldTime) { // Trigger "extralong" hold

    if (not ExtralongHoldEventPast) {

        event = 5;

        ExtralongHoldEventPast = true;

    }

}

}

```

```

    }

    buttonLast = buttonVal;

    return event;
}

if (veryBeginning == 1) {

    event = 1;

    veryBeginning = 0;

    greenSingleledon();

    return event;

}

}

/*void check_switches()

{

    static byte previousstate[NUMBUTTONS];

    static byte currentstate[NUMBUTTONS];

    static long lasttime;

    byte index;

    if (millis() < lasttime) { // we wrapped around, lets just try again

        lasttime = millis();

    }

    if ((lasttime + DEBOUNCE) > millis()) { // not enough time has passed to debounce

        return;

    }

    lasttime = millis(); // ok we have waited DEBOUNCE milliseconds, lets reset the timer

    for (index = 0; index < NUMBUTTONS; index++) {

        justpressed[index] = 0; //when we start, we clear out the "just" indicators

        justreleased[index] = 0;

```

```

currentstate[index] = digitalRead(buttons[index]); //read the button
if (currentstate[index] == previousstate[index]) {
  if ((pressed[index] == LOW) && (currentstate[index] == LOW)) { // just pressed
    justpressed[index] = 1;
  }
  else if ((pressed[index] == HIGH) && (currentstate[index] == HIGH)) {
    justreleased[index] = 1; // just released
  }
  pressed[index] = !currentstate[index]; //remember, digital HIGH means NOT pressed
}
previousstate[index] = currentstate[index]; //keep a running tally of the buttons
}
}*/
/*byte thisSwitch_justPressed() {
  byte thisSwitch = 255;
  check_switches(); //check the switches & get the current state
  for (byte i = 0; i < NUMBUTTONS; i++) {
    current_keystate[i] = justpressed[i];
    if (current_keystate[i] != previous_keystate[i]) {
      if (current_keystate[i]) thisSwitch = i;
    }
    previous_keystate[i] = current_keystate[i];
  }
  return thisSwitch;
}*/
void blinktriggerLed()
{

```

```

for (i = 0; i < 6; i++)
{
    digitalWrite(Trigger_LED, HIGH);
    delay(Trigger_LED + triggerDelay);
    digitalWrite(Trigger_LED, LOW);
    delay(Trigger_LED + triggerDelay);
}
}

void SwitchCore()
{
    int val = 0;

    switch (SwitchSumButton) // 1 or 2 or 3 = 1 Select Loop - 2 Build Loop - 3 Save loop - + 1 to
6 buttonpressed
    {
        /****** BYPASS MODE */

        case 41:
            bypassMode(0);
            break;

        case 42:
            bypassMode(1);
            break;

        case 43:
            bypassMode(2);
            break;

        case 44:
            bypassMode(3);
            break;
    }
}

```

```
case 45:
    bypassMode(4);
    break;
case 46:
    bypassMode(5);
    break;
/***** BUILD PRESET MODE */
case 21:
    buildPresetMode(0);
    break;
case 22:
    buildPresetMode(1);
    break;
case 23:
    buildPresetMode(2);
    break;
case 24:
    buildPresetMode(3);
    break;
case 25:
    buildPresetMode(4);
    break;
case 26:
    buildPresetMode(5);
    break;
/***** STORE PRESET MODE */
case 31: //SaveLoop(int addr, int led)
```

```
    SaveLoop(11, ledPin[0]);

    break;

case 32:

    SaveLoop(21, ledPin[1]);

    break;

case 33:

    SaveLoop(31, ledPin[2]);

    break;

case 34:

    SaveLoop(41, ledPin[3]);

    break;

case 35:

    SaveLoop(51, ledPin[4]);

    break;

case 36:

    SaveLoop(61, ledPin[5]);

    break;

/***** READ PRESET MODE */

case 11: //(int addr, int pcNum, int led)

    LiveModePreset(11, 1, 0);

    EEPROM.write((150), 11); //save preset in use, at startup this preset will be selected

    break;

case 12:

    LiveModePreset(21, 2, 1);

    EEPROM.write((150), 12);

    break;

case 13:
```

```
    LiveModePreset(31, 3, 2);

    EEPROM.write((150), 13);

    break;
case 14:

    LiveModePreset(41, 4, 3);

    EEPROM.write((150), 14);

    break;
case 15:

    LiveModePreset(51, 5, 4);

    EEPROM.write((150), 15);

    break;
case 16:

    LiveModePreset(61, 6, 5);

    EEPROM.write((150), 16);

    break;
}
}

void buildtempLoop() {

    mute();

    delay(Dmute);

    for (int q = 0 ; q < 6 ; q++)

    {

        if (digitalRead(relayPin[q]) == HIGH) {    // check if the relay is HIGH

            digitalWrite(ledPin[q], HIGH); // turn LED ON

        } else {

            digitalWrite(ledPin[q], LOW); // else turn LED OFF

        }

    }

}
```

```

}

unmute();

delay(Dmute);

}

void BuildLoop(int relay) //old version of switch 21/26 - not used anymore left here "just in
case"

{

digitalWrite(relayPin[relay], ~state);

digitalWrite(ledPin[relay], ~state);

// delay(Dmute);

digitalWrite(relayPin[relay], state);

digitalWrite(ledPin[relay], state);

}

void LiveModePreset(int addr, int pcNum, int led) //k-o

{

mute();

delay(Dmute);

for (int i = 0; i < 6; i++)

{

digitalWrite(relayPin[i], EEPROM.read((addr) + i));

digitalWrite(ledPin[i], LOW);

digitalWrite(ledPin[led], HIGH);

delay(10);

}

delay(Dmute);

unmute();

}

```

```
void SaveLoop(int addr, int led)
{
    //please contact the author to get these part of the sketch. Sorry ;)
}

void AllPresetLedsOn() {
    for (int i = 0 ; i < 6 ; i ++ )
    {
        digitalWrite(ledPin[i], HIGH);
    }
}

void AllPresetLedsOff() {
    for (int i = 0 ; i < 6 ; i ++ )
    {
        digitalWrite(ledPin[i], LOW);
    }
}

void AllPresetRelaysOff() {
    for (int i = 0 ; i < 6 ; i ++ )
    {
        digitalWrite(relayPin[i], LOW);
    }
}

void AllPresetRelaysOn() {
    for (int i = 0 ; i < 6 ; i ++ )
    {
        digitalWrite(relayPin[i], HIGH);
    }
}
```

```

}

void startupBlinking() {
    mute();

    delay(Dmute);

    for (int q = 0 ; q < 2 ; q++)
    {
        for (int i = 6 ; i > 0 ; i --) {
            digitalWrite(ledPin[i - 1], HIGH);
            delay(100);
        }
        for (int i = 0 ; i < 6 ; i ++ ) {
            digitalWrite(ledPin[i], LOW);
            delay(100);
        }
    }

    for (int i = 0 ; i < 6; i++)
    {
        digitalWrite(relayPin[i], !digitalRead(relayPin[i]));
        delay(200);
    }

    for (int i = 0; i < 4; i++)
    {
        AllPresetLedsOn();

        delay(100);

        AllPresetLedsOff();

        delay(100);
    }
}

```

```
AllPresetRelaysOff();

for (int i = 0 ; i < 2; i++)

{

    digitalWrite(Trigger_LED, !digitalRead(Trigger_LED));

    delay(200);

}

unmute();

delay(Dmute);

delay(600);

}

void writetempEprom() { //delete before re lease final product

for (int i = 11 ; i < 67; i++)

{

    EEPROM.write((i), 0);

}

EEPROM.write((11), 0);

EEPROM.write((12), 1);

EEPROM.write((13), 0);

EEPROM.write((14), 0);

EEPROM.write((15), 1);

EEPROM.write((16), 0);

EEPROM.write((21), 0);

EEPROM.write((22), 0);

EEPROM.write((23), 1);

EEPROM.write((24), 1);

EEPROM.write((25), 0);
```

```
EEPROM.write((26), 0);
```

```
EEPROM.write((31), 0);
```

```
EEPROM.write((32), 0);
```

```
EEPROM.write((33), 0);
```

```
EEPROM.write((34), 0);
```

```
EEPROM.write((35), 1);
```

```
EEPROM.write((36), 0);
```

```
EEPROM.write((41), 0);
```

```
EEPROM.write((42), 0);
```

```
EEPROM.write((43), 1);
```

```
EEPROM.write((44), 0);
```

```
EEPROM.write((45), 0);
```

```
EEPROM.write((46), 0);
```

```
EEPROM.write((51), 0);
```

```
EEPROM.write((52), 1);
```

```
EEPROM.write((53), 1);
```

```
EEPROM.write((54), 1);
```

```
EEPROM.write((55), 0);
```

```
EEPROM.write((56), 0);
```

```
EEPROM.write((61), 0);
```

```
EEPROM.write((62), 0);
```

```
EEPROM.write((63), 0);
```

```
EEPROM.write((64), 1);
```

```
EEPROM.write((65), 0);

EEPROM.write((66), 0);

}

void greenSingleledon() {

    pinMode(Trigger_LED, OUTPUT);

    digitalWrite(Trigger_LED, HIGH); // turn the LED on (HIGH is the voltage level)

}

void greenSingleledoff() {

    pinMode(Trigger_LED, INPUT); // turn the LED off by making the voltage LOW

    delay(100); // wait for a 100th second

}

void redSingleledon() {

    pinMode(Trigger_LED, OUTPUT);

    digitalWrite(Trigger_LED, LOW); // turn the LED on (HIGH is the voltage level)

}

void redSingleledoff() {

    pinMode(Trigger_LED, INPUT); // turn the LED off by making the voltage LOW

    delay(100); // wait for a 100th second

}

void redSingleledblink() {

    for (i = 0 ; i < 6; i++)

    {

        redSingleledon();

        delay(triggerDelay);

        redSingleledoff();

    }

}
```

```
void greenSingleledblink() {
  for (i = 0 ; i < 6; i++)
  {
    greenSingleledon();
    delay(triggerDelay);
    greenSingleledoff();
  }
}

void mute()
{
  digitalWrite(mutePin, HIGH);
}

void unmute()
{
  digitalWrite(mutePin, LOW);
}

void byPassAll()
{
  delay(Dmute);
  mute();
  for (i = 0; i < 6; i++)
  {
    WPreseton = digitalRead(ledPin[i]);
    if (WPreseton == HIGH)
    {
      Preseton = i ;
      digitalWrite(ledPin[i], LOW);
    }
  }
}
```

```

    }
}
AllPresetRelaysOn();
AllPresetRelaysOff();
unmute();
delay(Dmute);
delay(500);
}
byte keypad() // function used to detect which button is used
{
    static bool no_press_flag = 0; //static flag used to ensure no button is pressed
    for (byte x = 0; x < columns; x++) // for loop used to read all inputs of keypad to ensure no
button is pressed
    {
        if (digitalRead(Input[x]) == HIGH); //read evry input if high continue else break;
        else
            break;
        if (x == (columns - 1)) //if no button is pressed
        {
            no_press_flag = 1;
            h = 0;
            v = 0;
        }
    }
    if (no_press_flag == 1) //if no button is pressed
    {
        for (byte r = 0; r < rows; r++) //for loop used to make all output as low

```

```

    digitalWrite(Output[r], LOW);

    for (h = 0; h < columns; h++) // for loop to check if one of inputs is low
    {
        if (digitalRead(Input[h]) == HIGH) //if specific input is remain high (no press on it)
        continue

        continue;

        else //if one of inputs is low
        {
            for (v = 0; v < rows; v++) //for loop used to specify the number of row
            {
                digitalWrite(Output[v], HIGH); //make specified output as HIGH

                if (digitalRead(Input[h]) == HIGH) //if the input that selected from first sor loop is
                change to high
                {
                    no_press_flag = 0; //reset the no press flag;

                    for (byte w = 0; w < rows; w++) // make all outputs as low

                    digitalWrite(Output[w], LOW);

                    return v * 4 + h; //return number of button

                }

            }

        }

    }

    return 50;

}

void bypassMode(int led)

{

    mute();

```

```

delay(Dmute);

digitalWrite(relayPin[led], !digitalRead(relayPin[led]));

digitalWrite(ledPin[led], !digitalRead(ledPin[led]));

delay(Dmute);

unmute();
}

void buildPresetMode(int led)
{
mute();

delay(Dmute);

digitalWrite(relayPin[led], !digitalRead(relayPin[led]));

digitalWrite(ledPin[led], !digitalRead(ledPin[led]));

delay(Dmute);

unmute();
}

void blinkledinByPassMode() {

static byte heartState = 1;

static unsigned long previousBeat = millis();

unsigned long currentMillis = millis();

if (currentMillis - previousBeat >= 1200) {

previousBeat = currentMillis;

heartState ^= 1;

//      digitalWrite(13, heartState);

//  pinMode(Trigger_LED, OUTPUT);

digitalWrite(Trigger_LED, heartState); // turn the LED on (HIGH is the voltage level)

}

}

```

```

void blinkLedfortesting()
{
  for (int q = 0 ; q < 2 ; q++)
  {
    for (int i = 6 ; i > 0 ; i --) {
      digitalWrite(ledPin[i - 1], HIGH);
      delay(100);
    }
    for (int i = 0 ; i < 6 ; i ++ ) {
      digitalWrite(ledPin[i], LOW);
      delay(100);
    }
  }
}

void blinkledpresetmod(int Pled) { // blinks led of preset selected to be modified

  static byte heartState = 1;

  static unsigned long previousBeat = millis();

  unsigned long currentMillis = millis();

  if (currentMillis - previousBeat >= beatdelay) {

    previousBeat = currentMillis;

    heartState ^= 1;

    //      digitalWrite(13, heartState);

    //  pinMode(Trigger_LED, OUTPUT);

    digitalWrite(ledPin[Pled], heartState); // turn the LED on (HIGH is the voltage level)

  }

}

```